



HarmonicDrive®

Hollow Structure Full Unit Type

SHF-11-50-2UH
SHF-11-100-2UH

The smallest model SHF-11 has been newly added in the lineup of HarmonicDrive® SHF-2UH series/unit type.

The smallest model SHF-11 has been newly developed, which features structure of larger hollow opening diameter. Accordingly, the lineup of HarmonicDrive® SHF-2UH series/full unit type has been enhanced. Securing hollow opening diameter $\phi 14\text{mm}$ same as the

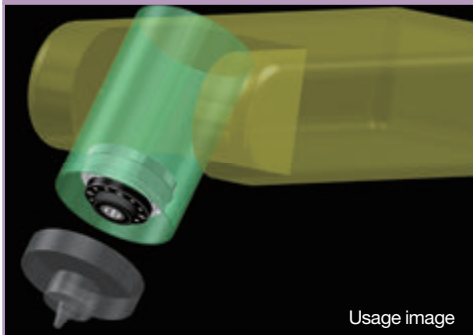
previously smallest model SHF-14-2UH, we introduce this new model that can offer wider range of use. The smallest model SHF-11 can meet customer's versatile needs, such as air piping, electric wiring, penetration of optical fiber cable, combination with ball screw, and other usages.

Main Market

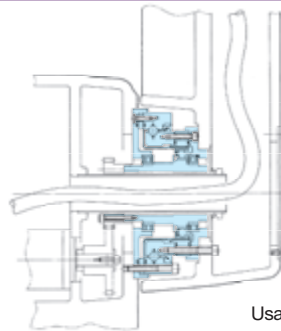
Industrial Robot

Semiconductor Manufacturing Equipment

Vertical Articulated Robot

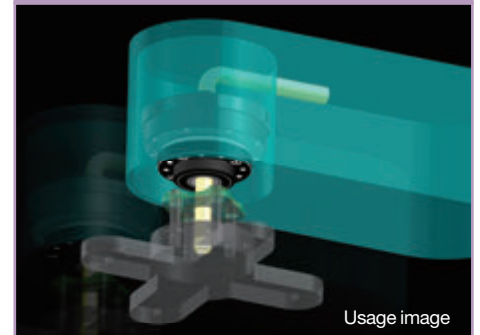


Usage image



Usage image

Wafer absorption carrier equipment



Usage image



■ SHF-11-XXX-2UH Specification

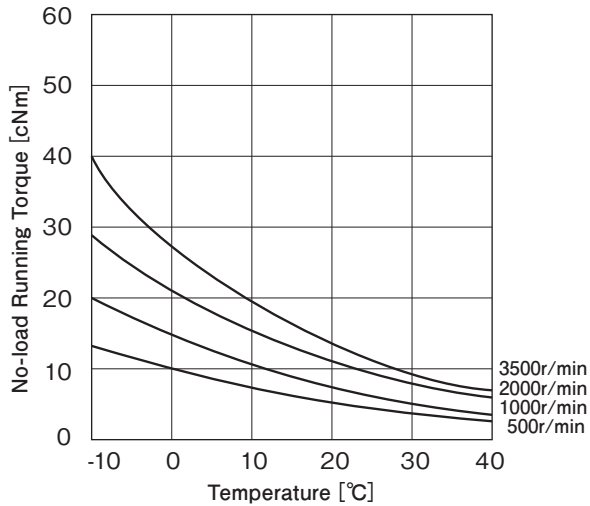
Features		Unit	Reduction Ratio		
			50	100	
Rated Torque in 2000r/min Input		Nm	3.5	5	
		kgfm	0.36	0.51	
Permissible Peak Torque in Starting or Stopping		Nm	8.3	11	
		kgfm	0.85	1.12	
Permissible Maximum Value of Average Load Torque		Nm	5.5	8.9	
		kgfm	0.56	0.91	
Momentary Permissible Maximum Torque		Nm	17	25	
		kgfm	1.73	2.55	
Permissible Max. Input Rotational Speed	Grease Lubrication	r/min	8500	8500	
Permissible Ave. Input Rotational Speed	Grease Lubrication	r/min	3500	3500	
Angular Transmission Accuracy		$\times 10^{-3}$ rad	0.58	0.44	
		arc min	2	1.5	
Hysteresis Loss		$\times 10^{-4}$ rad	5.8	5.8	
		arc min	2.0	2.0	
Starting Torque		cNm	7.1	5.9	
Speed-up Starting Torque		Nm	4.6	7.6	
Stiffness		T1	Nm	0.8	
			kgfm	0.082	
		T2	Nm	2.0	
			kgfm	0.20	
		K1	$\times 10^4$ Nm/rad	0.22	0.27
			kgfm/arc min	0.066	0.080
		K2	$\times 10^4$ Nm/rad	0.30	0.34
			kgfm/arc min	0.090	0.10
		K3	$\times 10^4$ Nm/rad	0.32	0.44
			kgfm/arc min	0.096	0.13
		$\theta 1$	$\times 10^{-4}$ rad	3.6	3.0
			arc min	1.2	1.0
		$\theta 2$	$\times 10^{-4}$ rad	8.0	6.0
			arc min	2.6	2.2
Ratcheting Torque		Nm	34	43	
Buckling Torque		Nm	90		
Mass		kg	0.53		
Moment of Inertia		I	$\times 10^{-4}$ kgm ²	0.008	
		J	$\times 10^{-5}$ kgfms ²	0.082	

■ Main Shaft Bearing Specification

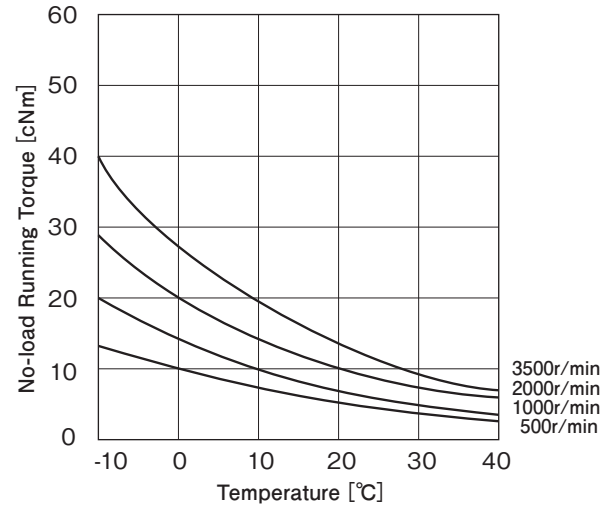
Features		Unit	
Pitch Circle Diameter of Roller	dp	m	0.043
Offset Amount	R	m	0.018
Basic Load Rating	Basic Dynamic Load Rating C	$\times 10^2$ N	52.9
		kgf	540
	Basic Static Load Rating Co	$\times 10^2$ N	75.5
		kgf	770
Permissible Moment Load Mc		Nm	74
		kgfm	7.6
Moment Stiffness Km		$\times 10^4$ Nm/rad	6.5
		kgfm/arc min	1.8

No-load Running Torque

■ SHF-11-50-2UH



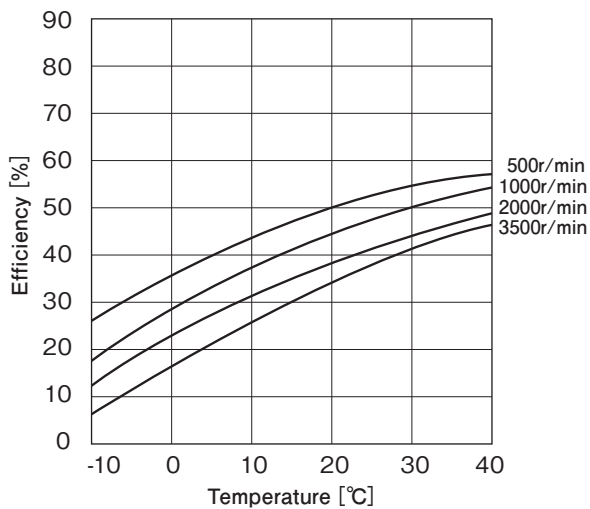
■ SHF-11-100-2UH



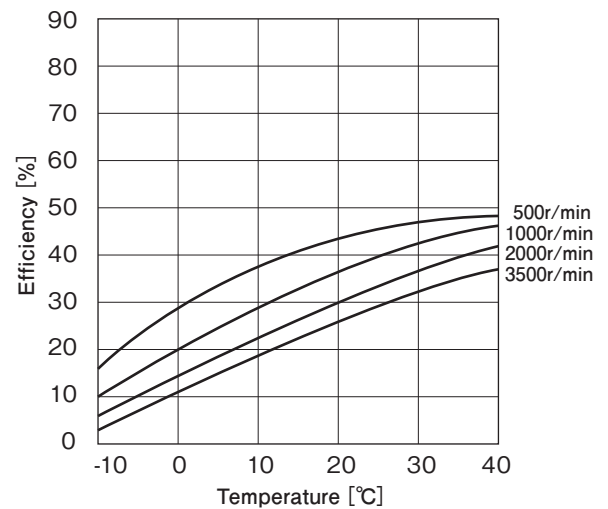
* The above graphs are based on calculated values. * Lubrication Grease: Harmonic Grease SK-2

Efficiency

■ SHF-11-50-2UH



■ SHF-11-100-2UH

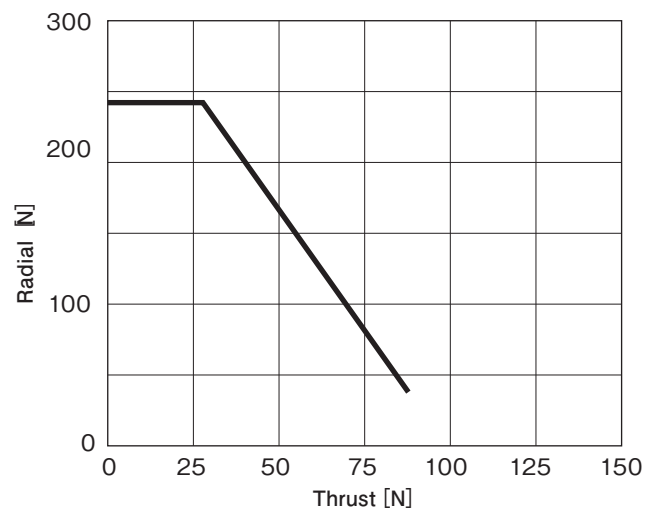


* The above graphs are based on calculated values. * Lubrication Grease: Harmonic Grease SK-2

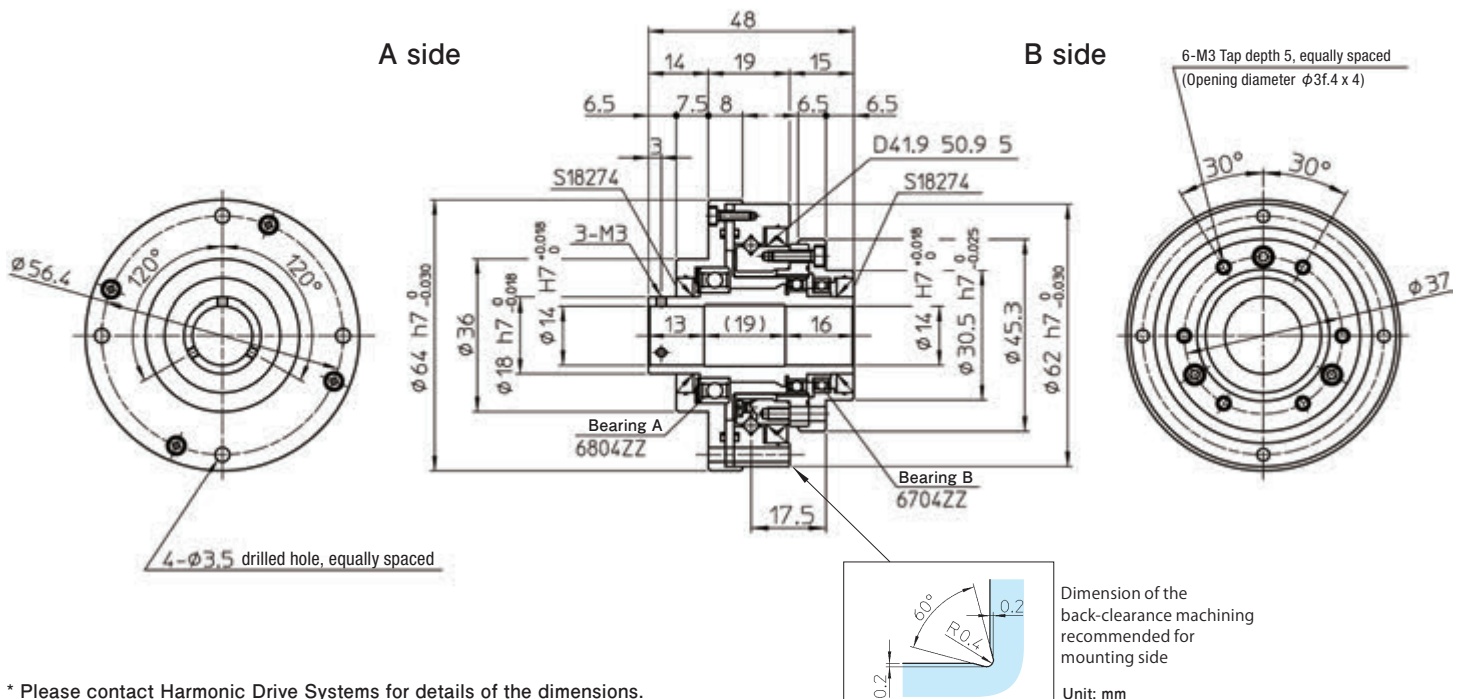
Permissible Load of Input Parts

Bearing	A	B
Nominal Number	6804ZZ	6704ZZ
Basic Dynamic Load Rating	Cr [N] 4000	1400
Basic Static Load Rating	Cor [N] 2470	720
Radial Load and Distance from Approaching Brg	[mm]	15.5
Distance between Brgs	[mm]	25.7

■ SHF-11-2UH



Dimensions



* Please contact Harmonic Drive Systems for details of the dimensions.

Mounting and Transmission Torque

Mounting Part		A side	B side
Applicable Bolt Size		M3	M3
Number of Bolt	Number	4	6
Bolt Mounting PCD	mm	56.4	37
Bolt Tightening Torque	Nm	2	2
	kgf-m	0.2	0.2
Bolt Transmission Torque	Nm	47	46
	kgf-m	4.7	4.6

Mounting Oil Seal Peripheral Part

Mount an oil seal to the mounting surface of the destination with 1mm or more clearance to prevent interfering each other.

* Please contact Harmonic Drive Systems for details.

Rotational Direction and Reduction Ratio

In unit type, rotational direction and reduction ratio varies depending on the flange to be fixed. Therefore, please check them before using.

1. Flex Spline Fixing

Input: Wave generator
Output: Circular spline
Fixing: Flex spline

Output rotational direction:
Same as that of input

$$\text{Reduction ratio: (i):i} = \frac{1}{R+1}$$

2. Circular Spline Fixing

Input: Wave generator
Output: Flex spline
Fixing: Circular spline

Output rotational direction:
Reverse direction as that of input

$$\text{Reduction ratio: (i):i} = \frac{-1}{R}$$



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